Depletion force in a bidisperse granular layer

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We demonstrate the effect of the depletion force in experiments and simulations of vertically vibrated mixtures of large and small steel spheres. The system exhibits size segregation and a large increase in the pair correlation function of the large spheres for short distances that can be accurately described using a combination of the depletion potential derived for equilibrium colloidal systems and a Boltzmann factor. The Boltzmann factor defines an effective temperature for the system, which we compare to other measures of temperature.

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Vibrated granular materials show many complex behaviors, including pattern formation, segregation, nonequipartition of energy, and non-Gaussian velocity distributions [1-3]. Many of these are purely nonequilibrium effects, but some features of vibrated granular materials are strikingly similar to equilibrium systems such as colloidal suspensions [1,4,5]. The extent to which the machinery of equilibrium statistical mechanics can be used as a starting point to develop a theory of these nonequilibrium steady states remains an open question.

Segregation mechanisms, meanwhile, are important in many industrial applications. Granular mixtures are known to segregate by size, mass, shape, and frictional coefficients and this segregation can be caused by many mechanisms, including vibration, convection, and tumbling [6,7]. In this paper we investigate a relatively unexplored mechanism for segregation in granular materials: the depletion force. Well studied in colloidal systems [8-11], the depletion force is an entropic effect in which the introduction of small particles into a colloidal dispersion will cause the larger colloidal particles to segregate. Previous suggestions of the role of the depletion force in granular materials have focused on horizontally shaken [12–14] or horizontally swirled [15] mixtures. The segregation effects for the horizontally vibrated mixtures, however, has been shown to be caused by a differential driving mechanism [16], which may also hold for the horizontally swirled system. The depletion force has also been implicated in vertically vibrated granular mixtures, where the Brazil nut effect is also present [17]. In this paper we show that the depletion force can cause size segregation in a vertically vibrated, bidisperse granular layer. Following analyses from experiments on colloidal suspensions [10], the pair correlation function for low concentrations of the large particles can be accurately described using the depletion potential derived for equilibrium systems and a Boltzmann factor. This Boltzmann factor defines an effective temperature for the system, which we compare to other measures of temperature in the system.

The depletion force was originally proposed by Asakura and Oosawa in 1954 [8]. There are two approaches for deriving the potential: the first is thermodynamic and the second is mechanical. In the thermodynamic view, illustrated in Fig. 1, the depletion force is derived through entropy maximization. There is a shell of width r_s (the radius of the smaller particles) around the large spheres into which the centers of the small spheres cannot penetrate. By arranging two large spheres together, the excluded volume regions of the two large spheres overlap, and the volume accessible to the small spheres increases, increasing the total entropy of the system. This produces an effective attraction between the large spheres. The mechanical view of the depletion force is that the small spheres exert a pressure on the large spheres, but that pressure is unbalanced when two large spheres are close enough together that the small spheres are excluded from the space between the spheres. The net force is found by integrating the pressure over the surface of the large spheres. In equilibrium, both views are equivalent and give the following expression for the depletion potential for two large spheres separated by a distance r, valid for moderately low densities of small spheres:

$$U(r) = \begin{cases} \infty & r < 2r_L \\ PV_{ex} & 2r_L < r < 2r_L + 2r_s \\ 0 & 2r_L + 2r_s < r \end{cases}$$
(1)



FIG. 1. (Color online) Schematic drawing of the depletion interaction. The white shell around the large particles represents the volume from which the small particles are excluded. The dark region shows the overlap in this excluded volume when the large particles are close together.

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FIG. 2. (Color online) Segregation due to the depletion force. Top panel: Experiment (ρ_s =0.036, ρ_L =0.066). Bottom panel: Simulations (ρ_s =0.080, ρ_L =0.132). In both instances the large and small spheres were initially randomly distributed throughout the available space. ν =30 Hz, Γ =3.5, r_L =4 mm, r_L/r_s =3.33, h=2.3 r_L .

where r_L is the radius of the large spheres, P is the pressure exerted on the large spheres by the small spheres, and V_{ex} is the overlap in excluded volume. V_{ex} can be expressed as

$$V_{ex}(r) = \frac{-4\pi(r_s + r_L)^3}{3} \left[1 - \frac{3r}{4(r_L + r_s)} + \frac{r^3}{16(r_s + r_L)^3} \right].$$
(2)

Our experimental setup consists of steel spheres of two sizes placed between two horizontal plates which are vibrated sinusoidally in the vertical direction. Images captured by a high resolution digital camera are analyzed to find the positions of the large spheres. For a range of ball diameters, as well as a range of both large and small ball volume fractions, we observe segregation of the large spheres. Figure 2 shows the results of one such experiment, where large spheres initially distributed randomly on the plate have formed a compact cluster. The parameter values, including the gap between the bottom and top plates, h, the vibration frequency, ν , the dimensionless acceleration $\Gamma = A(2\pi\nu)^2/g$, where A is the vibration amplitude, and the volume fraction of large and small spheres, $\rho_{L,s} = N_{L,s}V_{L,s}/V$, where $V_{L,s}$ is the volume of the large or small spheres and V is the volume of the system, are given in the figure caption. The segregation behavior is relatively insensitive to the frequency and amplitude of the acceleration, but is sensitive to the gap spacing. For spacings very close to the large ball diameter, friction with the top and bottom plates severely limits motion of the large spheres. For spacings significantly larger than the large sphere diameter, the kinetic energy of the large spheres is much larger than that of the small spheres, and the forces from the small spheres do not appreciably affect the trajectories of the large spheres. This strong deviation from equipartition is a consequence of the strong interaction with the vibrating plate experienced by all of the particles in the thin granular layers. Except as noted, all of the results presented below were taken with the parameters used for Fig. 2.

Because the system is highly sensitive to variations in the flatness of the plates, we also performed molecular dynamics simulations of the system to ensure that the segregation was not caused by such experimental issues, using a model that has been shown to reproduce the dynamics of similar granular experiments [1,4,18,19]. The force on a particle during a collision with another particle is calculated with the following equations:

$$\vec{F}_{normal} = (-\mu Y \xi - \mu \gamma \dot{\xi}) \hat{r}_{ij},$$
$$\vec{F}_{tangential} = -\mu \gamma_s \vec{v}_{ij}^t,$$

where μ is the reduced mass of the two particles, Y an elastic spring coefficient, ξ the particle overlap, γ a dissipative damping coefficient, and \hat{r}_{ij} a unit vector directed along the line connecting the centers of the interacting particles. \vec{v}_{ii}^t is the projection in the tangential direction of the relative velocities of the spheres at the point of contact. For the simulations reported, $Y=10^7$, in units of s⁻², and $\gamma=200$ and γ_s =100, in units of s^{-1} . For computational efficiency, the chosen Y creates spheres which are softer than those used in the experiment, but combines with the chosen γ to create a coefficient of restitution of 0.9, which is appropriate for colliding stainless steel spheres. The top and bottom of the system are treated as infinitely massive planes, while periodic boundary conditions were used in the lateral direction. The simulations produced phase segregation similar to that observed in the experiment, one example of which is shown in Fig. 2.

In equilibrium hard sphere systems, the depletion force can be measured directly by looking at the pair correlation function. If the density of large spheres is small enough that only two-particle interactions are present, then the large sphere pair correlation function, G(r), can be simply described through the use of a Boltzmann factor: G(r) $=\exp[-U(r)/T]$, in units where $k_{\rm B}=1$. In the nonequilibrium granular system, there is no reason to expect that this equilibrium approach should accurately describe the pair correlation function. Figure 3(a) shows an example of the pair correlation function measured in the experiment, showing a dramatic increase at small separations. G(r) measured in the simulation, shown in Fig. 3(b), shows a similar, although smaller, effect (note the difference in scale). The significant difference between the size of the peak in the simulation and the experiment is not understood, but may be related to the fact that, as noted above, the simulated spheres are considerably softer than the stainless steel balls used in the experiment.



FIG. 3. Pair correlation function of large particles and the fit using the a Boltzmann factor and the equilibrium depletion potential [Eq. (2)] (a) Experiment ($\rho_s = 0.071$, $\rho_L = 0.007$). (b) Simulations ($\rho_s = 0.08$, $\rho_L = 0.03$). Solid lines are fits to the equilibrium theory (see text).

The solid curve is a fit to $G(r) = \exp(-V_{ex}P/T)$, with V_{ex} given by Eq. (2) and P/T a fitting parameter that provides only an overall scale factor. The equilibrium-like approach accurately reproduces the width of the peak in G(r) and the overall shape of the curve. We have performed simulations with smaller and larger small spheres $(r_L/r_s=5.0 \text{ and } r_L/r_s)$ =2.0), and find, as expected, that range of the interaction is reduced in the former case and increased in the latter, but in both cases the agreement with the theoretical result is not as good as it is for r_L/r_s = 3.33. One way to quantify this is to let r_s in Eq. (2) be a free parameter. For simulations with r_s =0.2, 0.3, 0.5 r_L , we find r_s^{fit} =0.16±0.02, 0.3±0.03, $0.38 \pm 0.02 r_I$, respectively. (The uncertainties represent the standard deviation of fit values from multiple simulations.) The disagreement at large r_s is not surprising, as Eq. (2) is appropriate for large size ratios. The smaller discrepancy at smaller r_s is not understood, but the large differences in particle masses may enhance nonequilibrium effects not accounted for by Eq. (2).

In the simulations, the pressure in the system can be calculated by use of the virial theorem [4,20],allowing an explicit calculation of an "effective temperature," T_{dep} , from the value of P/T obtained from the fit to G(r). In order to determine if this temperature is related to other fluctuations in the bidisperse system, we have measured three other effective temperatures in the computer simulations, the granular temperature of the small spheres, the granular temperature of the large spheres, and an effective temperature



FIG. 4. (Color online) Temperatures measured in the simulations of the granular system. (a) Velocity distributions of small and large particles in the simulations with the same parameters as in Fig. 3(c) $(v_0 = \sqrt{\langle v^2 \rangle})$. The solid line is a Gaussian distribution. (b) Average displacement $\langle x \rangle$ as a function of time for a large particle subjected to a constant external force, and mean squared displacement $\langle x^2 \rangle$ vs. time for an unforced particle (ρ_s =0.096, ρ_L =0.0026). (c) The granular temperatures of the small (black squares) and large (red circles) spheres and the fluctuation-dissipation temperature (green triangles) at different densities of the small spheres plotted vs. the effective temperature measured from for the depletion potential. (From lowest to highest T_{dep} : ρ_s =0.036, 0.060, 0.072, 0.097.)

defined through a fluctuation-dissipation relation. The granular temperatures are given by $m\langle v_i \rangle^2$, where v_i is one component of the particle velocity and *m* is its mass. The distributions of the horizontal velocity components for the large and small particles are shown in Fig. 4(a). Both are approximately Gaussian for small values of the velocity, and the small particles are well described by a Gaussian distribution over all of the accessible range. The smaller particles are less confined and hence have a more three-dimensional motion, which has been shown to lead to more nearly Gaussian velocity distributions [21].

The granular temperatures are compared to T_{dep} for several concentrations of small spheres in Fig. 4(c). The results show that, unlike either granular temperature, T_{dep} is a strong function of small sphere density. (Note that in the equilibrium theory the concentration of small spheres contributes to the depletion interaction only through the pressure, which is directly computed in our determination of T_{dep} .) We also investigated whether T_{dep} is related to an effective temperature determined by a fluctuation-dissipation relation. While the granular system is not in the linear nonequilibrium regime, some studies have found that fluctuation-dissipation measurements of the temperature can agree with the granular temperature [22,23]. In particular, in Ref. [23], it was found that the granular temperature of each species of particles in a binary granular gas matches the temperature calculated by applying the Einstein relation for that species. The Einstein relation connects the coefficient of viscous drag, k_{drag} , to the diffusion constant, D, through the temperature: $T = k_{drag}D$. In the simulations, we can apply a constant external force to a large sphere and measure k_{drag} using the relation F $=k_{\text{drag}}v_{\text{term}}$, where v_{term} is the terminal velocity. An example of the observed linear displacement vs. time in the presence of a constant external force is shown in Fig. 4(b). We can also measure the diffusion constant in the case of no external forces using the relation $\langle x^2 \rangle = 2Dt$. An example of this is also shown in Fig. 4(b). Combining these measurements gives us an independent measurement of temperature in the system: $T_{FD} = DF_{ext} / v_{term}$. As can be seen in Fig. 4(c), the fluctuationdissipation measurement of the temperature does not match the depletion temperature. Also, unlike the results described in Ref. [23], there is no agreement between the fluctuationdissipation temperature and either granular temperature, although it is relatively close to the value found for the large spheres. This difference may be due to the forcing or dissipation from the top and bottom boundaries, which were not present in the model of Ref. [23]. Similarly, in quasi-2D colloidal systems, the presence of the confining plates results in additional contributions to the depletion interaction [11] that have not been considered in the above calculations. In the equilibrium system analyzed in Ref. [11], these "threebody" interactions (the two large spheres and the confining wall) result in only a small correction to the depletion potential at the small sphere densities considered here.

As the density of small balls increases, the simple form of the equilibrium depletion potential shown in Eq. (2) is no longer accurate [24]. From an entropic point of view, the most favorable separations are those that allow integer numbers of small spheres to fit between large spheres. In colloidal suspensions this leads to additional peaks in the pair correlation function at integer multiples of the small sphere diameter. The magnitude of the oscillations has been calculated with a density functional approach [24] and directly measured in colloidal suspensions [10]. This many-body ef-



FIG. 5. Pair correlation function for large spheres for a simulation of a high concentration of small spheres ($\rho_s = 0.12$, $\rho_L = 0.026$). The smaller second peak in G(r) occurs at $r = 2r_L + 2r_s$ (indicated by the arrow), where exactly one small sphere fits in between the large spheres.

fect, which is not easy to explain from the mechanical arguments, produces a small peak in G(r) for $r=2r_L+2r_s$. This peak is visible in the pair correlation function determined from a simulation at a high density of small spheres, as shown in Fig. 5, demonstrating that subtle entropy-driven dynamics are observable in this far from equilibrium granular system. Interestingly, the reduction in G(r) at half-integer multiples of the small-sphere diameter seen in equilibrium [24] is not observed.

In summary, we have found direct evidence for the depletion force in a vibrated granular system. We observe segregation of large particles induced by the presence of small particles, and an increase in the pair correlation function of the large particles at low concentrations which is consistent with the equilibrium depletion potential. We also observe, for high concentrations of small particles, a second peak in the large particle pair correlation function that is characteristic of the depletion potential. Using an approach from equilibrium statistical mechanics, we measure an effective temperature for the system using the depletion potential and a Boltzmann factor. This effective temperature does not agree with the granular temperatures of either sized particle or with a measurement of the temperature with a simple fluctuationdissipation measurement. These observations suggest that the driving mechanisms of the depletion interaction can operate in far from equilibrium granular systems, but that the equilibrium tools for quantifying the effects of the depletion force need modification to account for nonequilibrium effects such as energy injection and dissipation.

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